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MAX-PLANCK-GESELLSCHAFT

AN INTRODUCTION TO THE DIFFERENT CAUSAL FRAMEWORKS IN NEUROIMAGING

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Why causality?

To paraphrase a old joke, there are two types of statisticians: those who do causal inference and those who lie about it.

(L Wasserman, *Journal of the American Statistical Association*, 1999)

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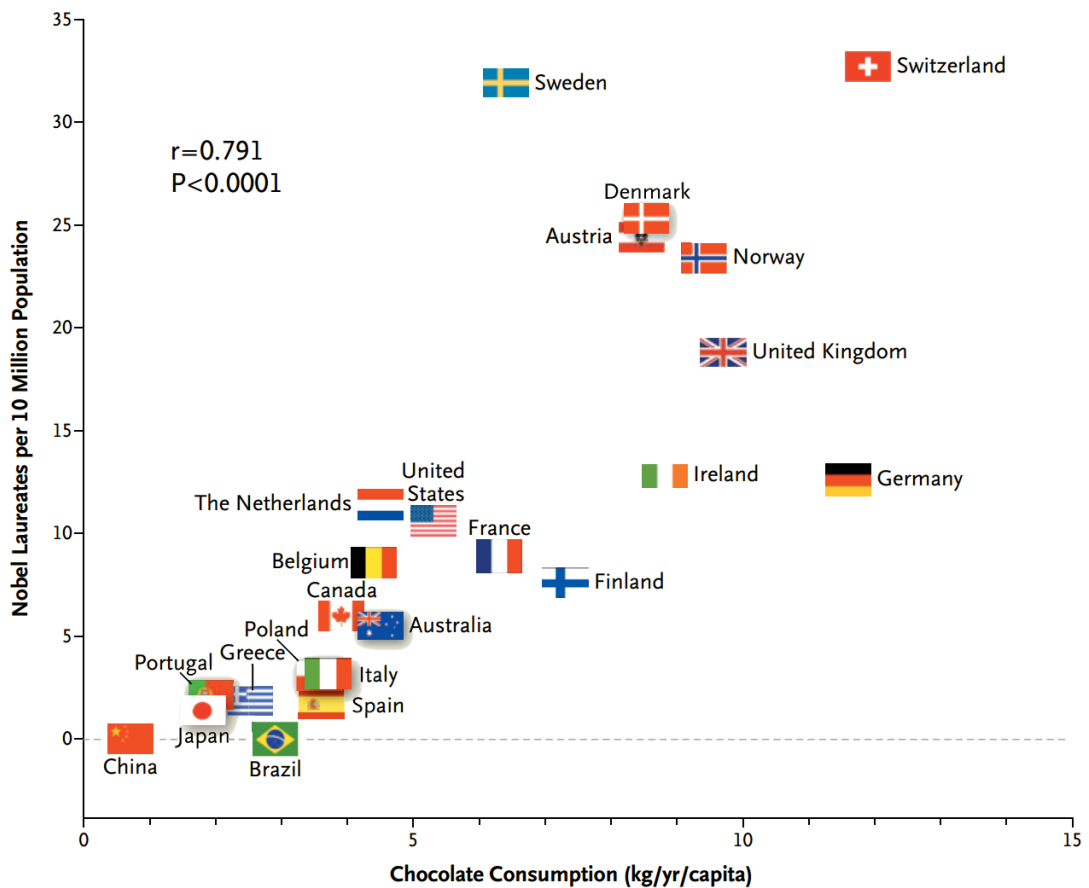


Figure 1. Correlation between Countries' Annual Per Capita Chocolate Consumption and the Number of Nobel Laureates per 10 Million Population.

A scientific theory should

- ▶ Explain already observed data
- ▶ Predict future observations
 - of a *passively* observed system
 - of a system that is *actively* intervened upon

We want to predict the effect of interventions!



Why causality? Goal of neuroimaging studies!



*Hippocampal activity in this study was correlated with amygdala activity, supporting the view that the amygdala **enhances** explicit memory by **modulating** activity in the hippocampus.*

(Anonymous Authors, *Trends in Cognitive Sciences*, 2001)

Common causal frameworks

Common causal frameworks

- ▶ Potential Outcomes Framework
- ▶ Granger Causality
- ▶ Dynamic Causal Modelling
- ▶ Causal Bayesian Networks and Structural Equation Models

Potential Outcomes Framework

Potential Outcomes Framework

Ingredients:

- ▶ Population \mathcal{U} of units $u \in \mathcal{U}$,
e. g. a patient group
- ▶ Treatment variable $S : \mathcal{U} \rightarrow \{t, c\}$,
e. g. assignment to treatment/control
- ▶ Potential outcomes $Y : \mathcal{U} \times \{t, c\} \rightarrow \mathbb{R}$,
e. g. survival times $Y_t(u)$ and $Y_c(u)$ of patient u

Fundamental problem of causal inference:

For each unit u we get to observe *either* $Y_t(u)$ *or* $Y_c(u)$ and hence the treatment effect $Y_t(u) - Y_c(u)$ cannot be computed.

Possible remedy assumptions:

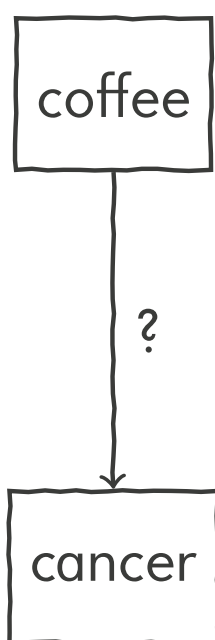
- ▶ Unit homogeneity: $Y_t(u_1) = Y_t(u_2)$ and $Y_c(u_1) = Y_c(u_2)$
- ▶ Causal transience: can measure $Y_t(u)$ and $Y_c(u)$ sequentially

“Statistical solution”: Average Treatment Effect $\mathbb{E}[Y_t] - \mathbb{E}[Y_c]$

- ▶ Can observe $\mathbb{E}[Y_t|S = t]$ and $\mathbb{E}[Y_c|S = c]$
- ▶ which, when randomly assigning treatments, i. e. $(Y_t, Y_c) \perp S$,
- ▶ is equal to $\mathbb{E}[Y_t]$ and $\mathbb{E}[Y_c]$.

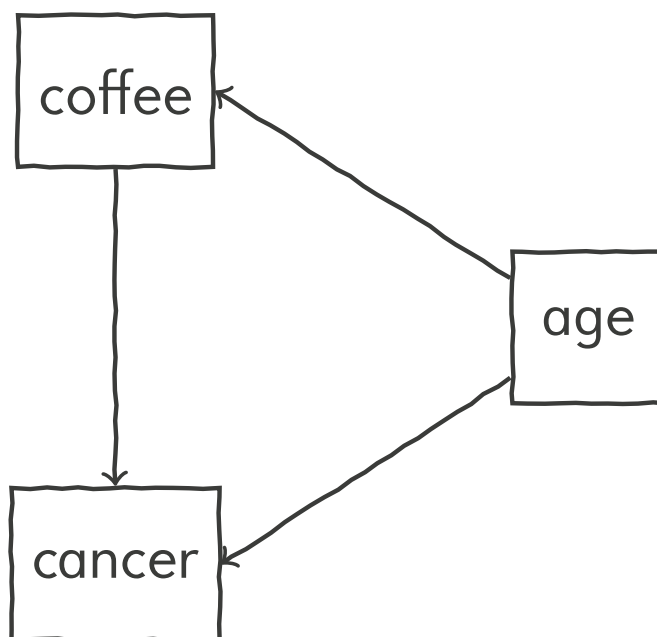
(PW Holland, Statistics and Causal Inference. *Journal of the American Statistical Association*, 1986)

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- ▶ Split population \mathcal{U} into
 - 'consumed little': $S(u) = \square$
 - 'consumed lots': $S(u) = \blacksquare$
- ▶ Observe whether they suffer from cancer or not, $Y \in \{0, 1\}$
- ▶ Assume older units have higher cumulative coffee consumption as well as an increased risk of cancer



- ▶ Split population \mathcal{U} into
 - 'consumed little': $S(u) = \square$
 - 'consumed lots': $S(u) = \blacksquare$
 - ▶ Observe whether they suffer from cancer or not, $Y \in \{0, 1\}$
 - ▶ Assume older units have higher cumulative coffee consumption as well as an increased risk of cancer
 - $(Y_{\square}, Y_{\blacksquare}) \not\perp S$
 - $\mathbb{E}[Y_{\square} | S = \square] < \mathbb{E}[Y_{\square}]$
- $\implies \mathbb{E}[Y_{\blacksquare}] - \mathbb{E}[Y_{\square}]$ systematically overestimates the effect of cumulative coffee consumption on cancer

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Common causal frameworks

- ▶ Potential Outcomes Framework
 - may work under certain (untestable) assumptions
- ▶ Granger Causality

- ▶ Dynamic Causal Modelling

- ▶ Causal Bayesian Networks and Structural Equation Models

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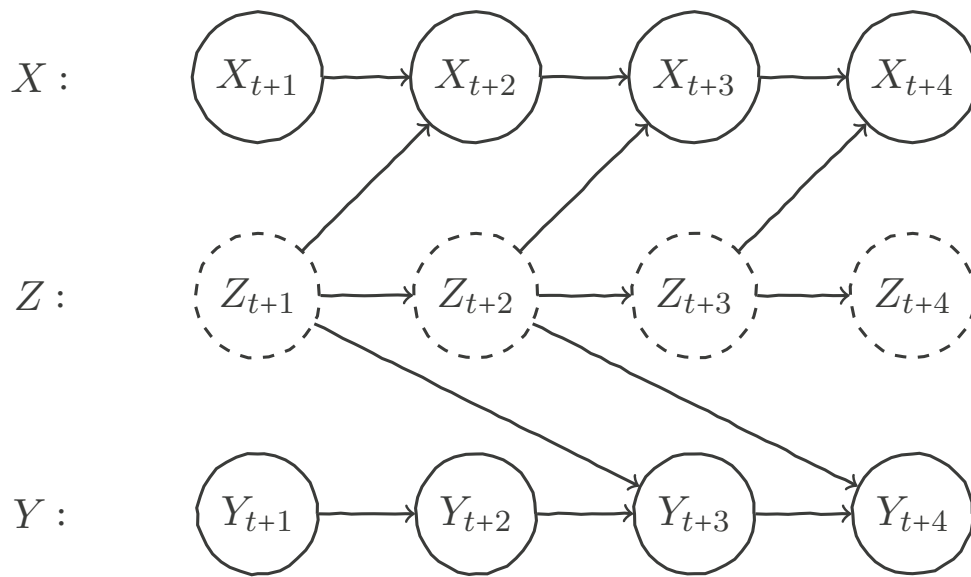
Granger Causality

Granger Causality

Simplified Definition: One stochastic process X is causal to a second Y if the autoregressive predictability of the second process at a given time point is improved by *including* measurements from the past of the first, i. e. if

$$\text{PredAcc}[Y_t|Y_{<t}] < \text{PredAcc}[Y_t|Y_{<t}, X_{<t}]$$

(*not* by C Granger)



$$\text{PredAcc}[Y_t|Y_{<t}] < \text{PredAcc}[Y_t|Y_{<t}, X_{<t}]$$

Granger causality erroneously infers causal influence from X to Y !

(J Peters et al. Causal discovery on time series using restricted structural equation models. *NIPS*, 2013)

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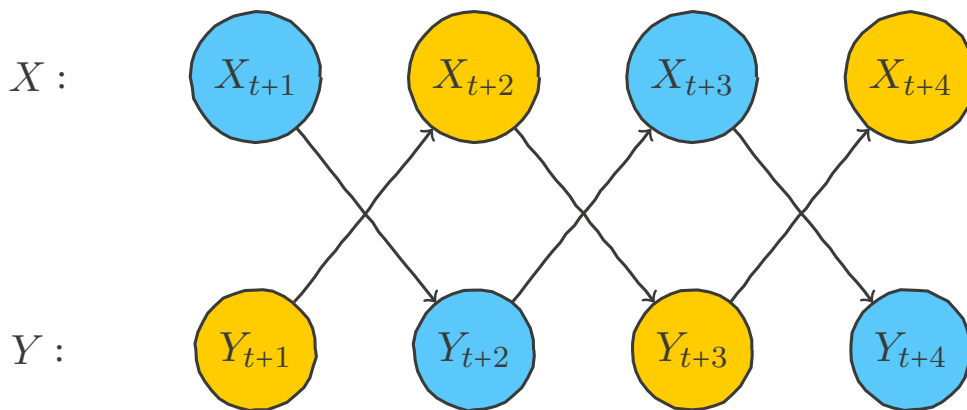
$$\text{PredAcc}[Y_t|Y_{<t}] < \text{PredAcc}[Y_t|Y_{<t}, X_{<t}]$$

(not by C Granger)

Granger's Definition: One stochastic process X is causal to a second Y if the predictability of the second process at a given time point is worsened by *removing* past measurements of the first from the universe's past, i. e. if

$$\text{PredAcc}[Y_t|\mathbb{R}_{<t}] > \text{PredAcc}[Y_t|\mathbb{R}_{<t} \setminus X_{<t}]$$

(by C Granger)



$$\text{PredAcc}[Y_t | \mathbb{O}_{<t}] = \text{PredAcc}[Y_t | \mathbb{O}_{<t} \setminus X_{<t}]$$

Granger causality fails to predict the effects of interventions!

(N Ay and D Polani, Information flows in causal networks. *Advances in Complex Systems*, 2008)

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Common causal frameworks

- ▶ Potential Outcomes Framework
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Dynamic Causal Modelling

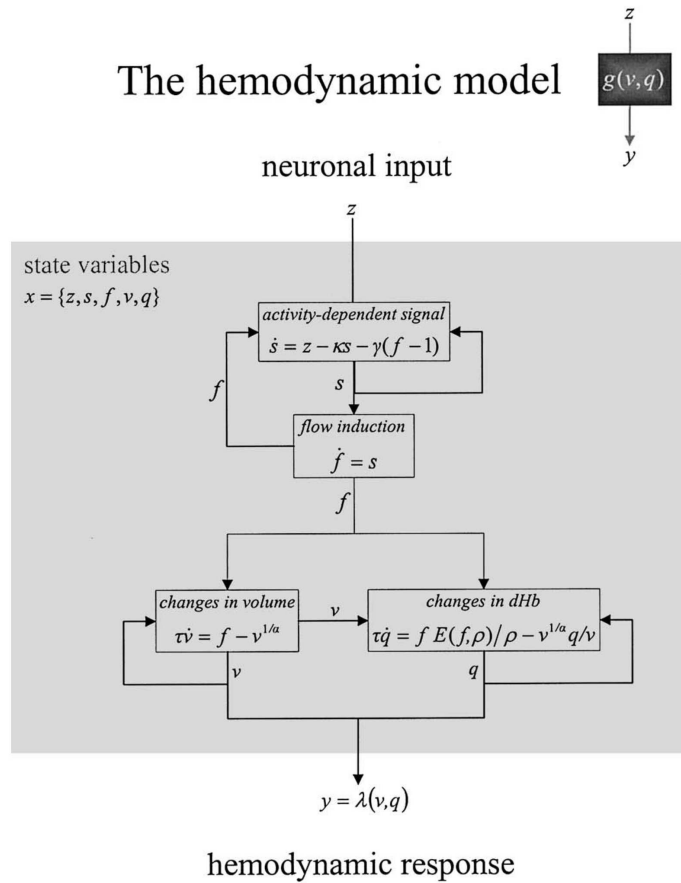
Causality in DCM is used in a control theory sense and means that, under the model, activity in one brain area causes dynamics in another, and that these dynamics cause the observations.

(Friston, *PLOS Biology*, 2009)

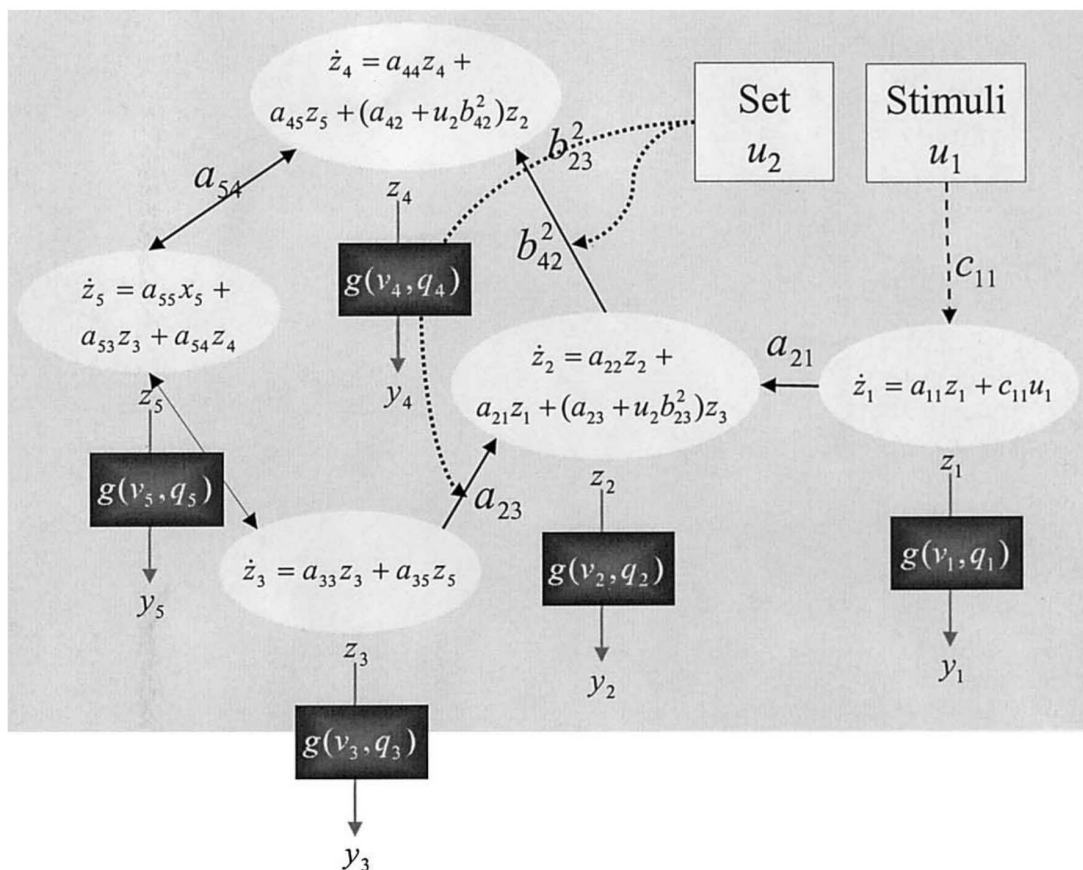
Inference procedure:

- ▶ Observe
- ▶ Define models $\mathcal{M} = \{M_1, \dots, M_N\}$
- ▶ Fit models to observed data
- ▶ Best fitting model \widehat{M} wins

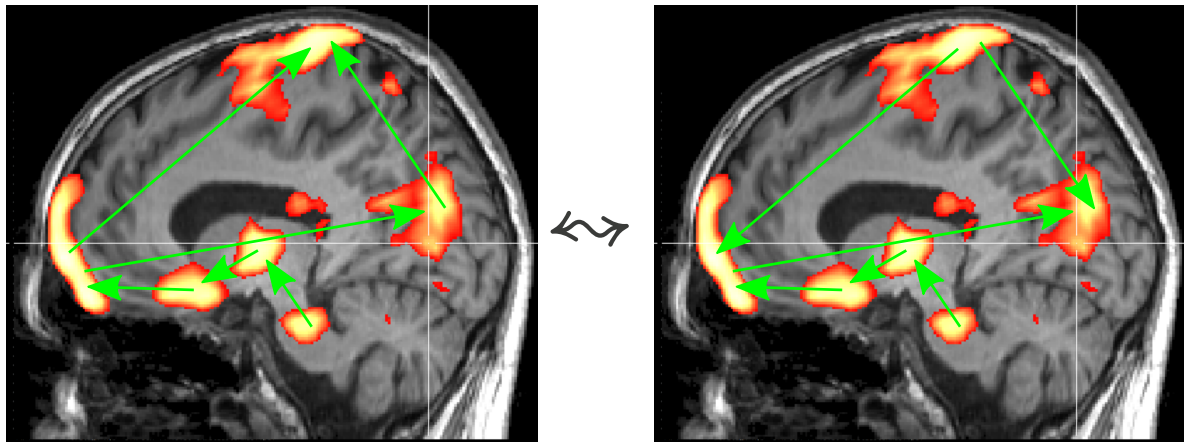
The hemodynamic model



(KJ Friston et al., Dynamic Causal Modelling. *NeuroImage*, 2003)



(KJ Friston et al., Dynamic Causal Modelling. *NeuroImage*, 2003)



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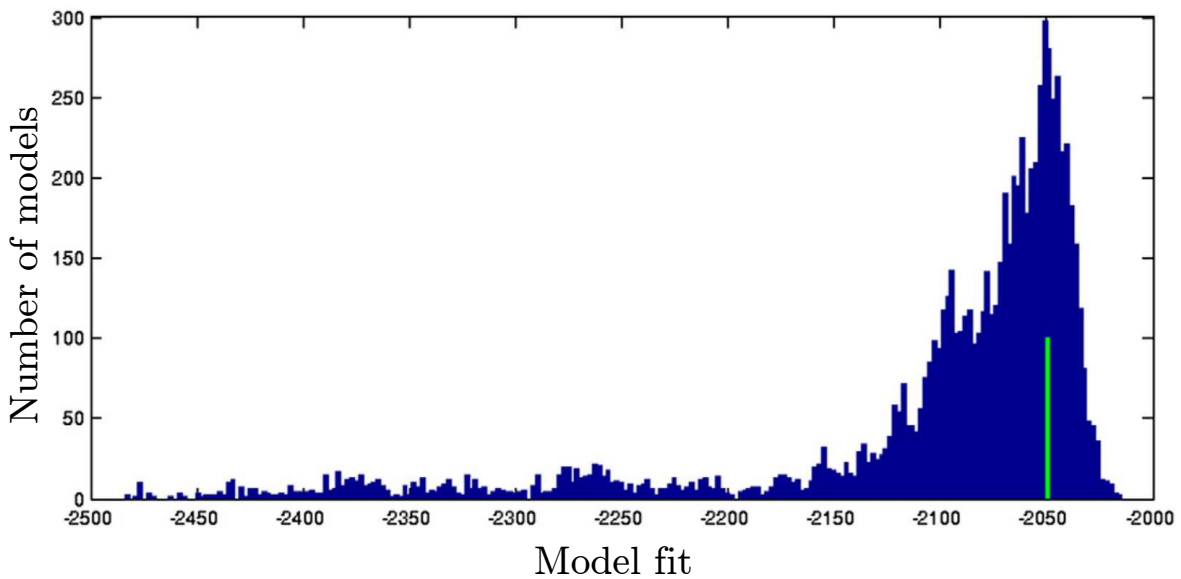
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Inference procedure:

- ▶ Observe
- ▶ Define models $\mathcal{M} = \{M_1, \dots, M_N\}$
- ▶ Fit models to observed data
- ▶ Best fitting model \widehat{M} wins

Is \widehat{M} guaranteed to reflect the true connectivities?



⇒ Similar model fit does not translate into similar connectivities!

(Lohmann et al., Critical comments on dynamic causal modelling. *NeuroImage*, 2012)

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Causal Bayesian Networks and Structural Equation Models

Structural Equation Models

A Structural Equation Model (SEM) $\mathcal{M}_X = (\mathcal{S}_X, \mathcal{I}_X, \mathbb{P}_{E_X})$ with

- ▶ structural equations \mathcal{S}_X ;
- ▶ a set of interventions \mathcal{I}_X ;
- ▶ exogenous variables distributed according to \mathbb{P}_{E_X}

induces distributions \mathbb{P}_X over the X variables for each $i \in \mathcal{I}_X$.

$$\mathcal{M}_X = (\mathcal{S}_X, \mathcal{I}_X, \mathbb{P}_{E_X})$$

- ▶ $\mathcal{S}_X = \begin{cases} X_1 = E_1 \\ X_2 = X_1 + E_2 \end{cases}$
- ▶ $\mathcal{I}_X = \{\emptyset, \text{do}(X_1 = 5), \text{do}(X_2 = 3)\}$
- ▶ $E \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$

observational

intervention on X_1

intervention on X_2

$$\mathbb{P}_{X_1}^{\emptyset} \sim \mathcal{N}(0, 1)$$

$$\mathbb{P}_{X_1}^{\text{do}(X_1=5)} \equiv 5$$

$$\mathbb{P}_{X_1}^{\text{do}(X_2=3)} \sim \mathcal{N}(0, 1)$$

$$\mathbb{P}_{X_2}^{\emptyset} \sim \mathcal{N}(0, 2)$$

$$\mathbb{P}_{X_2}^{\text{do}(X_1=5)} \sim \mathcal{N}(5, 1)$$

$$\mathbb{P}_{X_2}^{\text{do}(X_2=3)} \equiv 3$$

(J Pearl, *Causality: Models, reasoning, and inference*, 2000; P Spirtes et al., *Causation, Prediction, and Search*, 2001)

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Causal Bayesian Networks

Definition of Cause and Effect

$$X \rightarrow Y \iff \mathbb{P}_Y^{\text{do}(X=x)} \neq \mathbb{P}_Y^{\emptyset} \text{ for some } x$$

Causal Markov Condition

d-separation \rightsquigarrow independence

Faithfulness

d-separation \Leftarrow independence

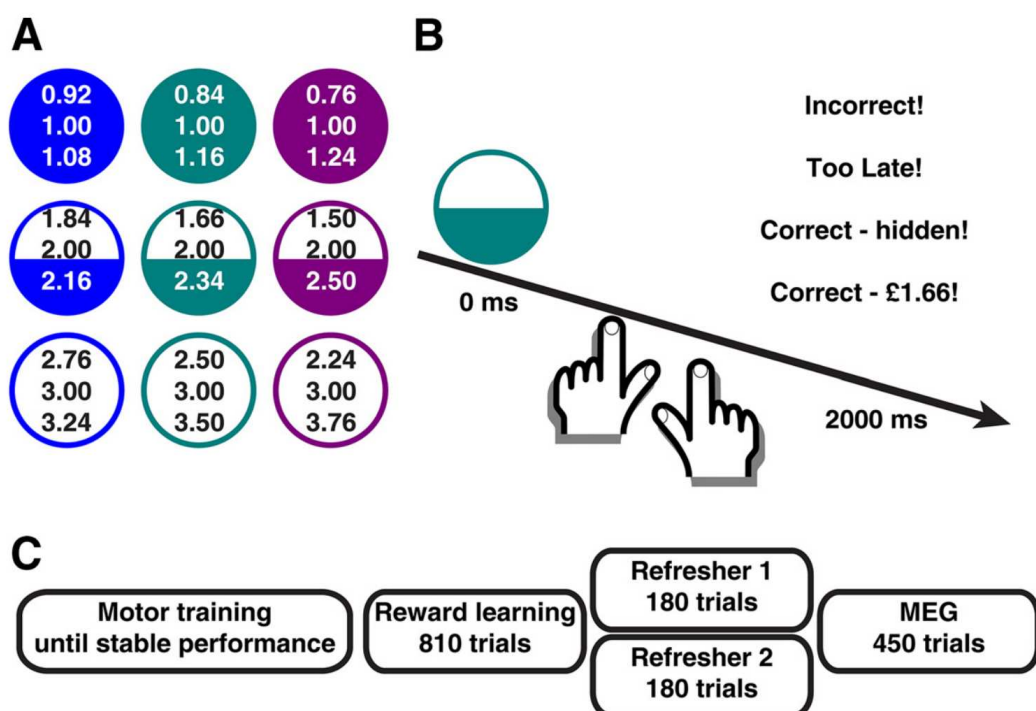
| chain | fork | collider |
|---------------------------------|--------------------------------|--------------------------------|
| $X \rightarrow Y \rightarrow Z$ | $X \leftarrow Y \rightarrow Z$ | $X \rightarrow Y \leftarrow Z$ |
| $X \not\perp Z$ | $X \not\perp Z$ | $X \perp Z$ |
| $X \perp Z Y$ | $X \perp Z Y$ | $X \not\perp Z Y$ |

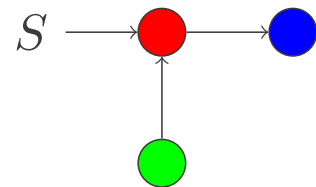
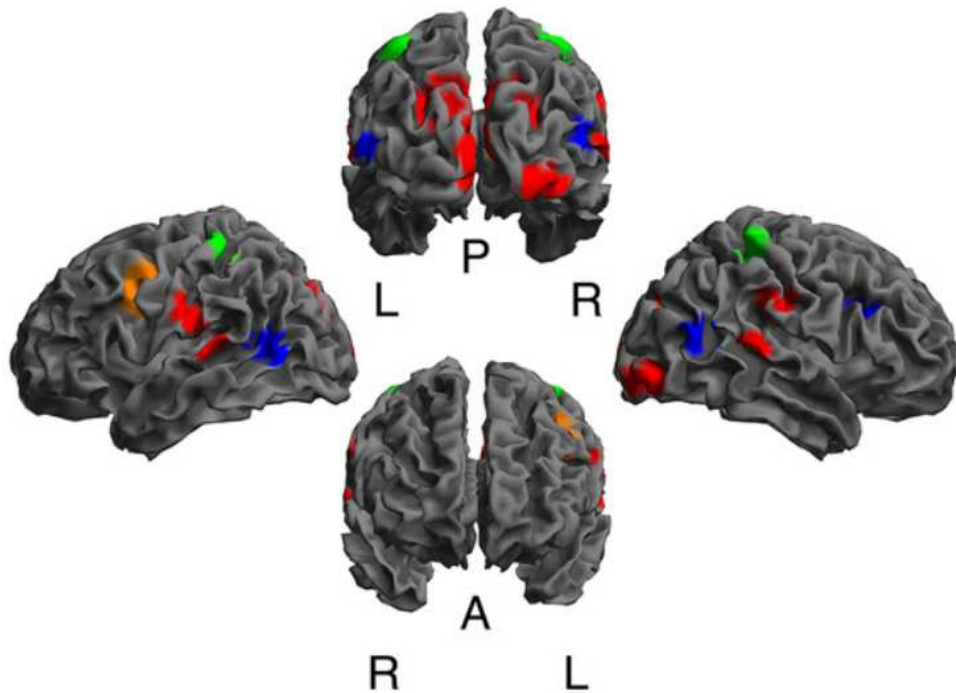
- ▶ Randomised stimulus S
 - ▶ Observe neural activity X and Y
 - ↪ Estimate $\mathbb{P}_{S,X,Y}^{\emptyset}$
 - ▶ Assume we find
 - $S \not\perp X \implies$ existence of path between S and X w/o collider
 - $S \not\perp Y \implies$ existence of path between S and Y w/o collider
 - $S \perp Y|X \implies$ all paths between S and Y blocked by X
 - ▶ Can rule out cases such as $S \rightarrow X \leftarrow h \rightarrow Y$
 - ▶ Can formally prove that X indeed is a cause of Y
- \implies Robust against hidden confounding

(M Grosse-Wentrup et al., *NeuroImage*, 2015; S Weichwald et al., *IEEE Journal of Selected Topics in Signal Processing*, 2016)

Application: Neural Dynamics of Probabilistic Reward Prediction

Bach et al. • Probabilistic Reward Prediction



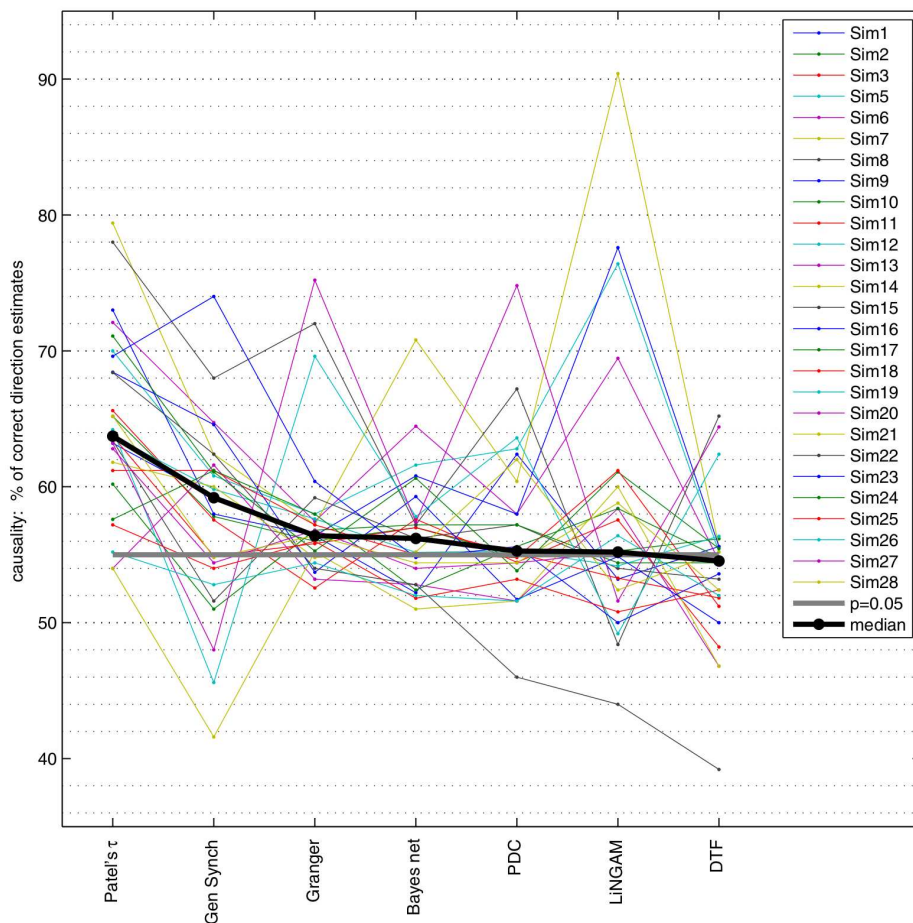


(Bach, Symmonds, Barnes, and Dolan, Whole-brain neural dynamics of probabilistic reward prediction. *Journal of Neuroscience*, 2017) 27

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 - may work under certain (untestable) assumptions
 - not finding dependence is not evidence for independence

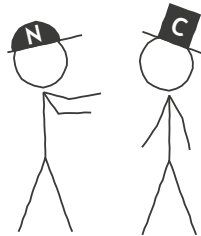
Wrap-Up



- ▶ (Causal) Inference rests on *untestable* assumptions.
- ▶ Causal inference algorithms appear to perform above chance-level.
- ▶ Causal inference may be useful to guide the design of interventional studies.



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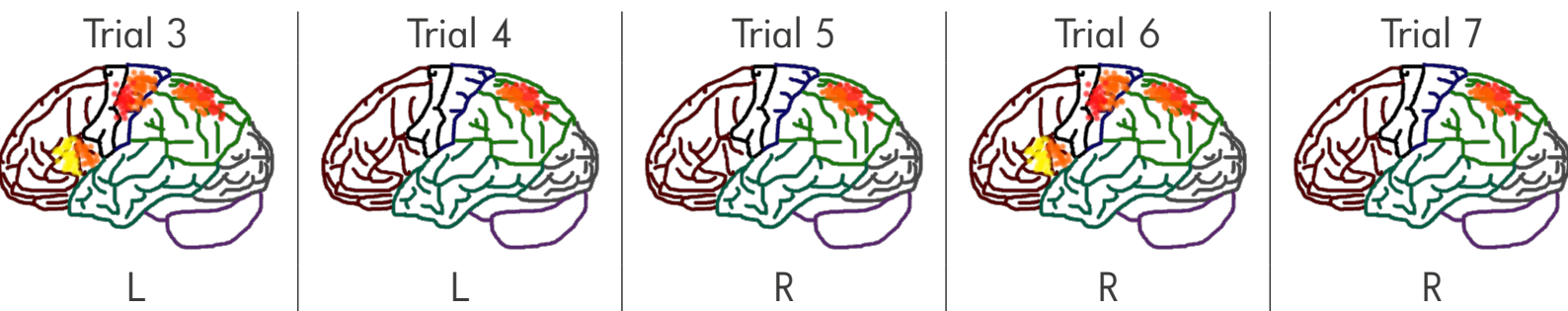


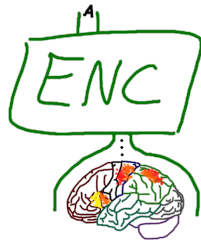
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ADDENDA

Causal interpretation of encoding and decoding models

Relevance in encoding and decoding models





“Significant variation explained by experimental condition?”

$$X_i \not\perp C$$

$$X_i \not\perp C | \vec{X} \setminus X_i$$

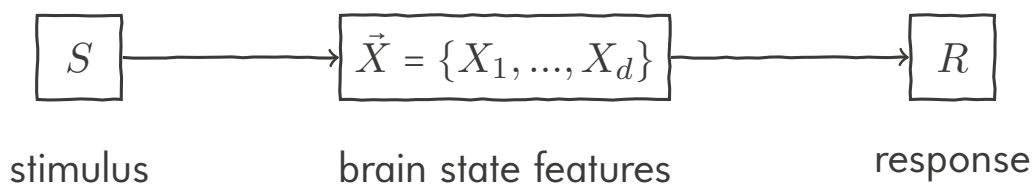
“Does removal impair decoding performance?”



relevant feature $\overset{?}{\rightleftarrows}$ cognitive process

(S Weichwald et al., Causal interpretation rules for encoding and decoding models in neuroimaging. *NeuroImage*, 2015)

A new distinction: stimulus- vs response-based



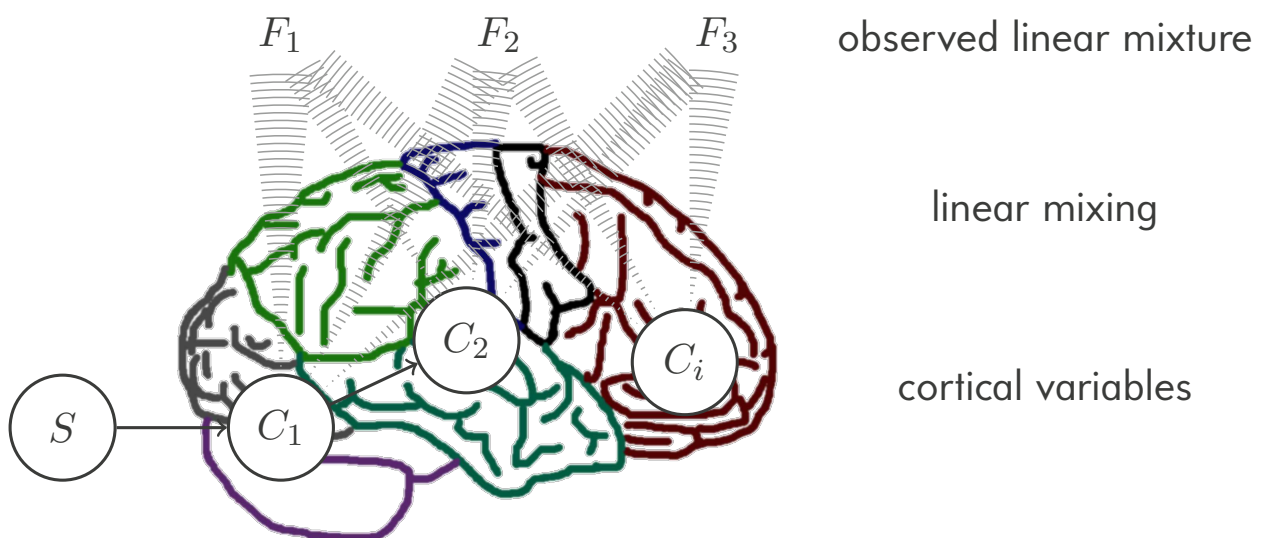
| stimulus-based | | response-based |
|--------------------|----------|--------------------|
| causal | encoding | <i>anti-causal</i> |
| <i>anti-causal</i> | decoding | causal |

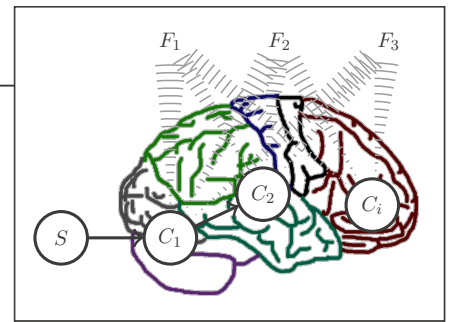
| | Feature X_i relevant? | | Causal interpretation |
|----------------|-------------------------|----------|-----------------------|
| | Encoding | Decoding | |
| Stimulus-based | × | | no effect of S |
| | ✓ | | effect of S |
| | | × | inconclusive |
| | | ✓ | inconclusive |
| Response-based | × | | no cause of R |
| | ✓ | | inconclusive |
| | | × | inconclusive |
| | | ✓ | inconclusive |

| | Feature X_i relevant? | | Causal interpretation |
|----------------|-------------------------|----------|------------------------|
| | Encoding | Decoding | |
| Stimulus-based | ✓ | ✓ | effect of S |
| | ✓ | × | indirect effect of S |
| | × | ✓ | provides context |
| | × | × | no effect of S |
| Response-based | ✓ | ✓ | inconclusive |
| | ✓ | × | no direct cause of R |
| | × | ✓ | provides context |
| | × | × | no cause of R |

MERLiN^{*}

Problem description





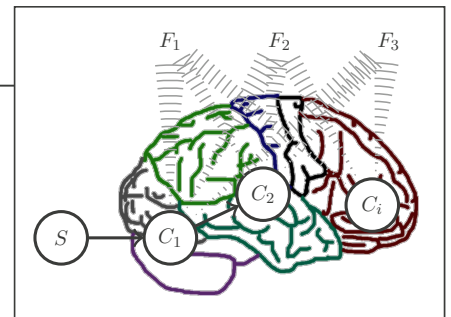
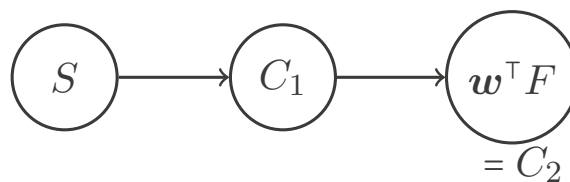
Given

samples of S, C_1 and F

$$F = \begin{bmatrix} F_1 \\ \vdots \\ F_d \end{bmatrix} = A \begin{bmatrix} C_1 \\ \vdots \\ C_d \end{bmatrix} = AC$$

Goal

find linear combination w such that



Idea

Optimise w such that

- (a) $\text{dep}(C_1, w^T F)$ is high
- (b) $\text{dep}(S, w^T F | C_1)$ is low

Implementation

Optimise w and σ, θ such that

$$\begin{aligned} & \text{HSIC}(C_1, w^T F) \quad \text{is high} \\ & - \text{HSIC}(w^T F - \text{krr}_{\sigma, \theta}(C_1), (S, C_1)) \text{ is low} \end{aligned}$$

is being maximised.