



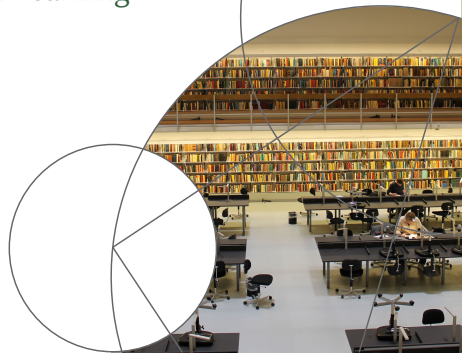
UNIVERSITY OF COPENHAGEN

Causal Models under Variable Transformations

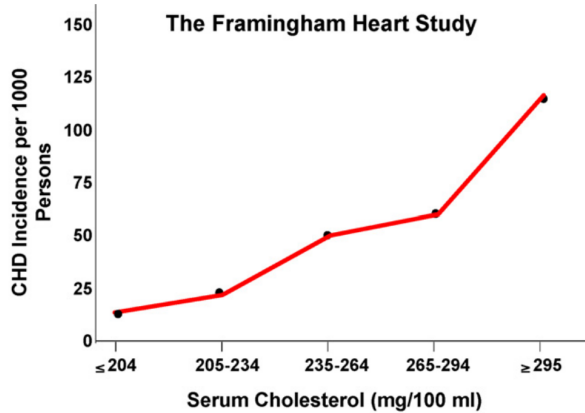
Challenges for *Causally Consistent* Representation Learning

Sebastian Weichwald

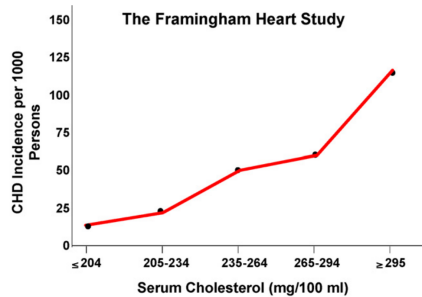
✉ sweichwald.de 🐦 [@sweichwald](https://twitter.com/sweichwald)







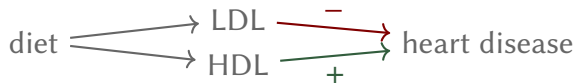




Variable Transformations may break Causal Reasoning ⚡



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diet \longrightarrow total chol. $\xrightarrow[-]{+}$ heart disease



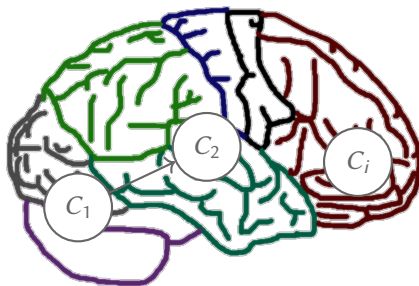
diet $\begin{cases} \longrightarrow \text{LDL} \\ \longrightarrow \text{HDL} \end{cases}$ $\begin{matrix} \xrightarrow{-} \\ \xrightarrow{+} \end{matrix}$ heart disease



Observables may not be (meaningful) Causal Entities ⚡



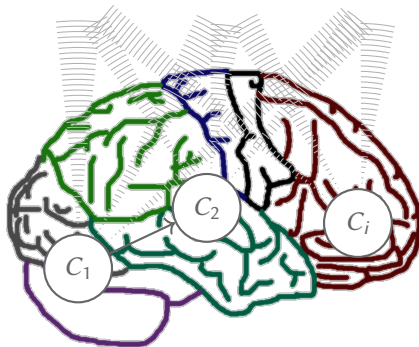
Observables may not be (meaningful) Causal Entities ⚡



causal entities



Observables may not be (meaningful) Causal Entities ⚡

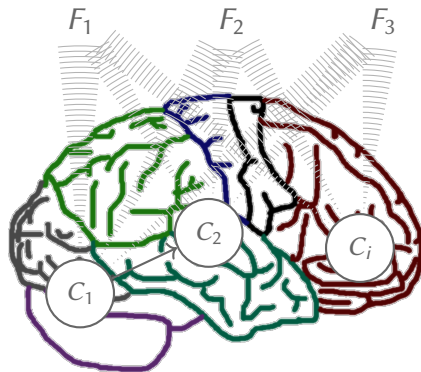


linear mixing

causal entities



Observables may not be (meaningful) Causal Entities ⚡



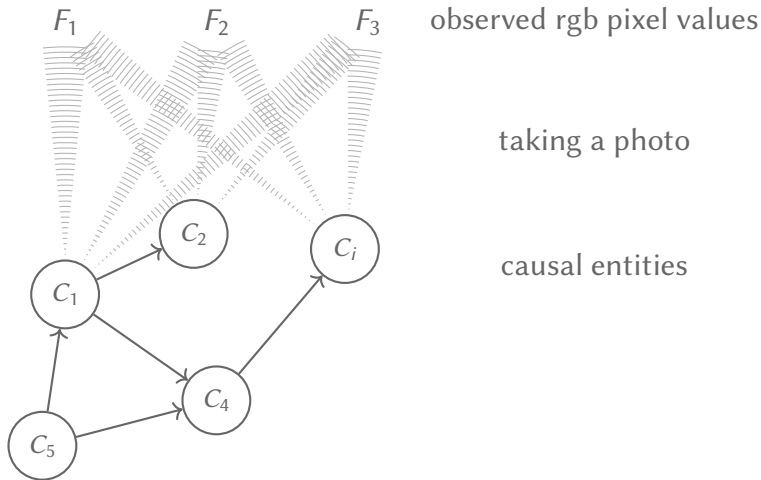
observed linear mixture

linear mixing

causal entities



Observables may not be (meaningful) Causal Entities ⚡



Challenges

Process:

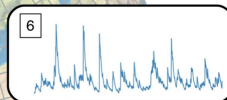
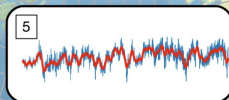
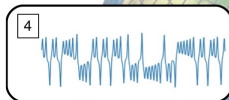
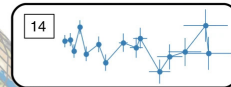
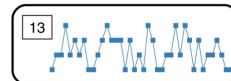
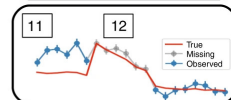
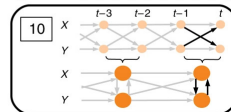
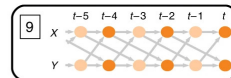
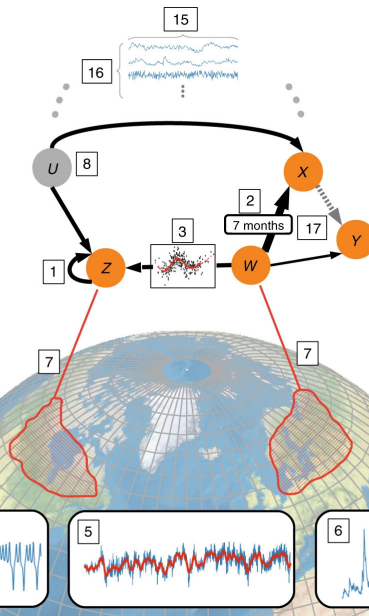
- 1 Autocorrelation
- 2 Time delays
- 3 Nonlinear dependencies
- 4 Chaotic state-dependence
- 5 Different time scales
- 6 Noise distributions

Data:

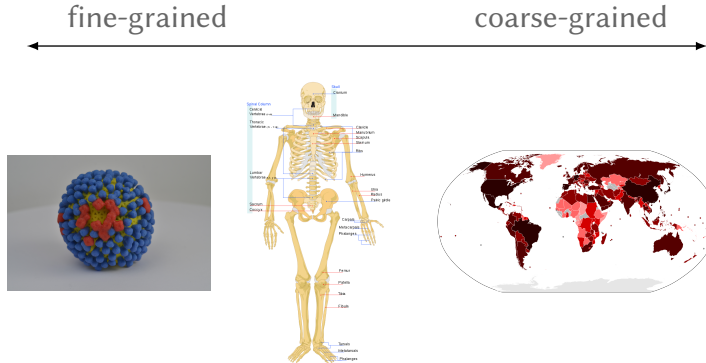
- 7 Variable extraction
- 8 Unobserved variables
- 9 Time subsampling
- 10 Time aggregation
- 11 Measurement errors
- 12 Selection bias
- 13 Discrete data
- 14 Dating uncertainties

Computational/statistical:

- 15 Sample size
- 16 High dimensionality
- 17 Uncertainty estimation



Variable Transformations may link Causal Reasoning at Different Scales



Causal Consistency of Structural Equation Models

auai.org/uai2017/proceedings/papers/11.pdf



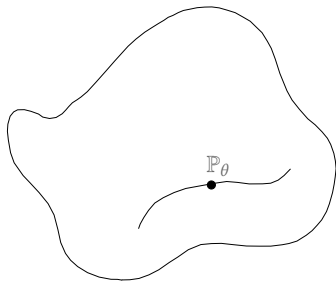
Paul Rubenstein, S Weichwald, S Bongers, JM Mooij,
D Janzing, M Grosse-Wentrup, B Schölkopf



Causal Models as Posets of Distributions

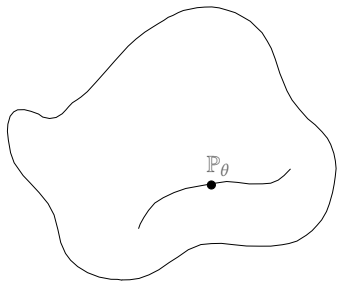
“Normal” Probabilistic Model:

$$\mathcal{M}_X : \theta \mapsto \mathbb{P}_\theta$$



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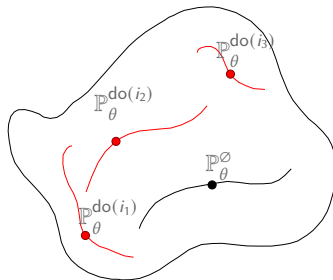
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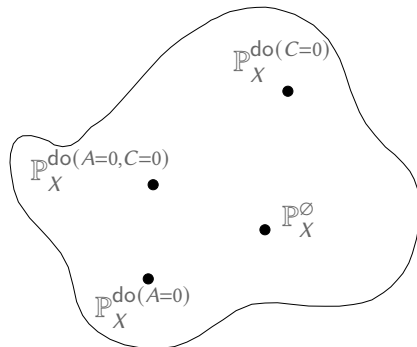
Causal Model:

$$\mathcal{M}_X : \theta \mapsto \{\mathbb{P}_\theta^{\text{do}(i)} : i \in \mathcal{I}_X\}$$

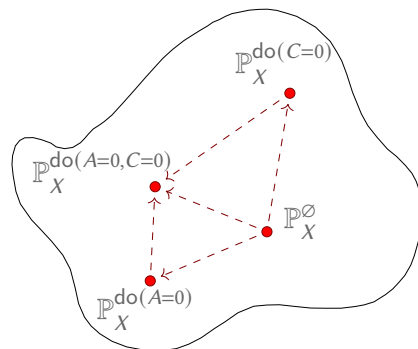
\mathcal{I}_X is set of **interventions**.



Causal Models



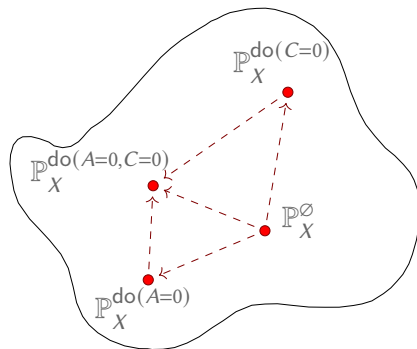
Causal Models



\mathcal{I}_X has **partial ordering** structure



Causal Models



\mathcal{I}_X has **partial ordering** structure

\mathcal{M}_X implies the **poset of distributions** $\mathcal{P}_X := \left(\left\{ \mathbb{P}_X^{\text{do}(i)} : i \in \mathcal{I}_X \right\}, \leq_X \right)$



Structural Causal Models

$$\mathcal{M}_X = (\mathcal{S}_X, \mathcal{I}_X, \mathbb{P}_{E_X})$$



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observational

$$\mathbb{P}_{X_1}^{\emptyset} \sim \mathcal{N}(0, 1)$$

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$$\mathbb{P}_{X_1}^{\text{do}(X_1=5)} \equiv 5$$

$$\mathbb{P}_{X_2}^{\text{do}(X_1=5)} \sim \mathcal{N}(5, 1)$$



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intervention on X_2

$$\mathbb{P}_{X_1}^{\text{do}(X_2=3)} \sim \mathcal{N}(0, 1)$$

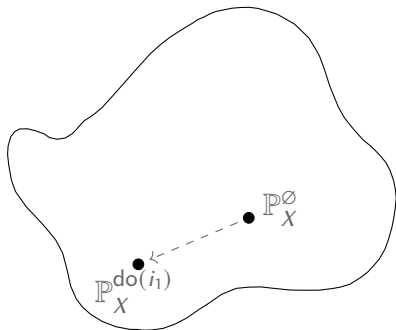
$$\mathbb{P}_{X_2}^{\text{do}(X_2=3)} \equiv 3$$



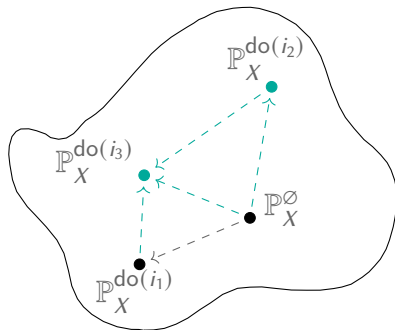
causal discovery?

observations

causal model

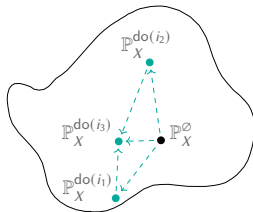


$$\left\{ \mathbb{P}_X^{\text{do}(i)} : i \in \mathcal{I}_{\text{sub}} \subsetneq \mathcal{I}_X \right\}$$

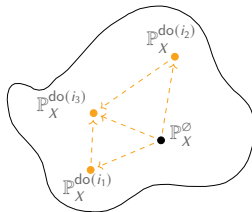
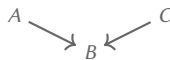


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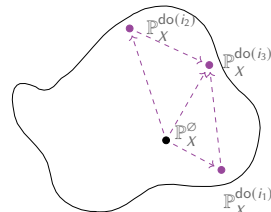
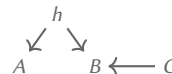




$$\begin{aligned}
 A &= \frac{1}{2}B - \frac{1}{2}C + \sqrt{\frac{3}{2}}N_A \\
 B &= \sqrt{3}N_B \\
 C &= \frac{1}{3}B + \sqrt{\frac{2}{3}}N_C
 \end{aligned}$$

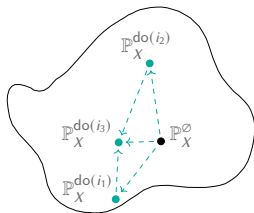


$$\begin{aligned}
 A &= \sqrt{2}N_A \\
 B &= \frac{1}{2}A + C + \sqrt{\frac{3}{2}}N_B \\
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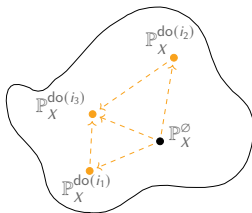
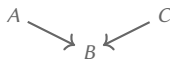


$$\begin{aligned}
 A &= h + N_A \\
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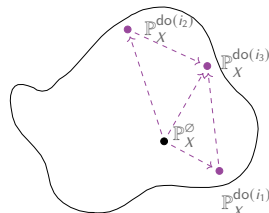
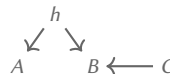




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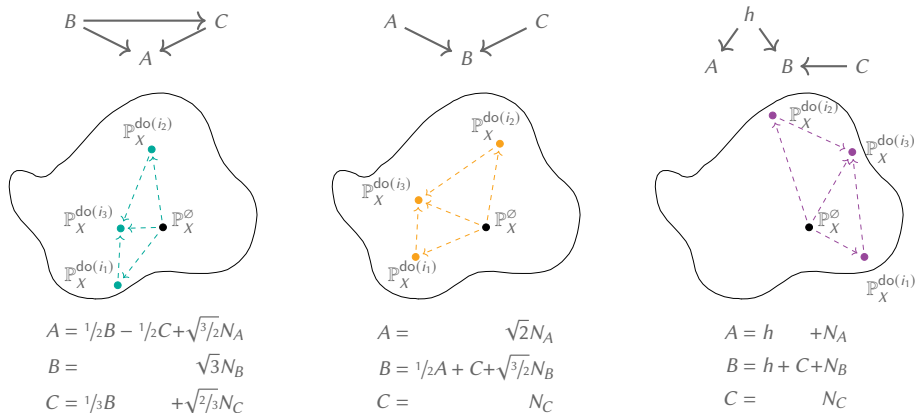
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↷ 3 models inducing the same observational yet different interventional distributions





↪ 3 models inducing the same observational yet different interventional distributions

fitting observational data well is not enough ⚡



NEEDED: ALGEBRA OF DOING

Available: algebra of **seeing**

e.g., What is the chance it rained
if we **see** the grass wet?

$$P(\text{rain} \mid \text{wet}) = ? \quad \{ = P(\text{wet} \mid \text{rain}) \frac{P(\text{rain})}{P(\text{wet})} \}$$

Needed: algebra of **doing**

e.g., What is the chance it rained
if we **make** the grass wet?

$$P(\text{rain} \mid \text{do}(\text{wet})) = ? \quad \{ = P(\text{rain}) \}$$



The Three Layer Causal Hierarchy

Level (Symbol)	Typical Activity	Typical Questions	Examples
1. Association $P(y x)$	Seeing	What is? How would seeing X change my belief in Y ?	What does a symptom tell me about a disease? What does a survey tell us about the election results?
2. Intervention $P(y do(x), z)$	Doing Intervening	What if? What if I do X ?	What if I take aspirin, will my headache be cured? What if we ban cigarettes?
3. Counterfactuals $P(y_x x', y')$	Imagining, Retrospection	Why? Was it X that caused Y ? What if I had acted differently?	Was it the aspirin that stopped my headache? Would Kennedy be alive had Oswald not shot him? What if I had not been smok- ing the past 2 years?



The Three Layer Causal Hierarchy

presupposes that X and Y are *the right* variables

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$X \sim \mathbb{P}_X$ an r.v. in $\mathcal{X} \implies \tau(X) \sim \mathbb{P}_{\tau(X)}$ is an r.v. in \mathcal{Y}



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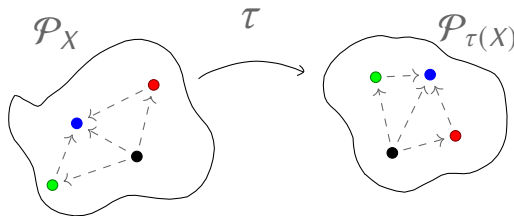


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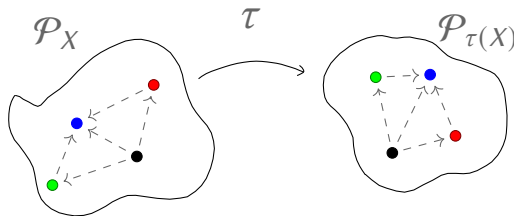


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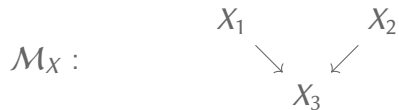


Does there exist an SCM \mathcal{M}_Y with $\mathcal{P}_Y = \mathcal{P}_{\tau(X)}$?

If so, then \mathcal{M}_Y will agree with our observations of \mathcal{M}_X via τ .



What can go wrong?



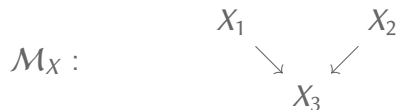
$$\mathcal{S}_X = \begin{cases} X_1 = E_1 \\ X_2 = E_2 \\ X_3 = X_1 + X_2 + E_3 \end{cases}$$

$E_2 = 1$; E_1, E_3 arbitrary

$$\mathcal{I}_X = \begin{cases} \text{do}(\emptyset) \\ \text{do}(X_1 = 0) \\ \text{do}(X_1 = 0, X_2 = 0) \end{cases}$$



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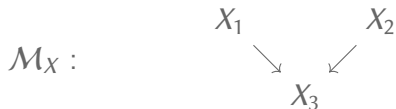
$\mathcal{M}_Y :$

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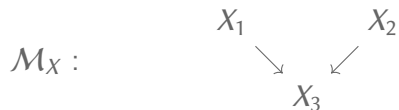
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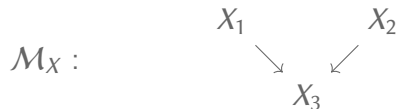
$$\mathcal{S}_Y = \begin{cases} Y_1 = E_1 + E_2 \\ Y_2 = Y_1 + E_3 \end{cases}$$

E_1, E_2, E_3 as before

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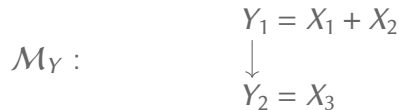
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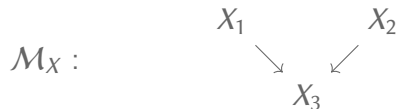
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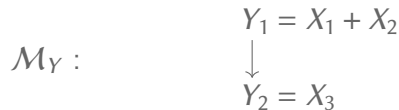
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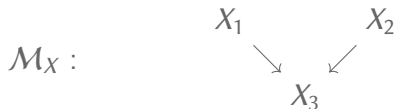
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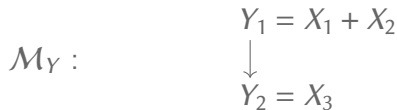
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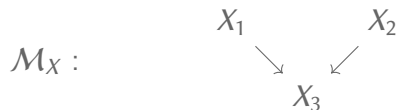
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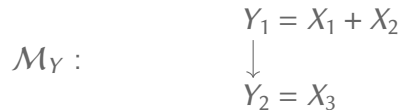
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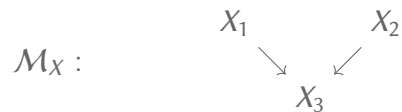
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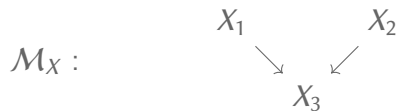


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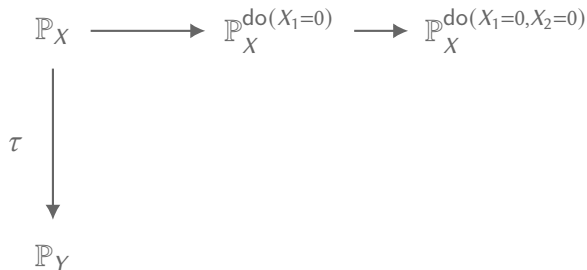
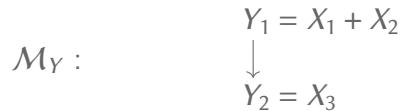
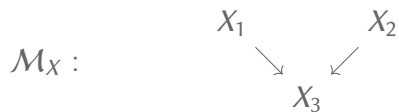
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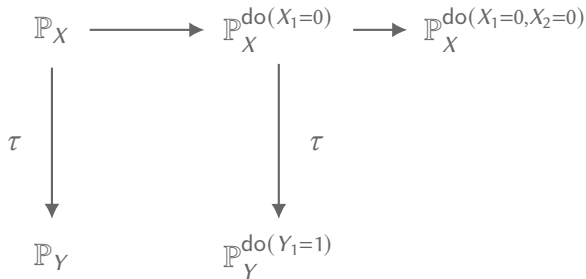
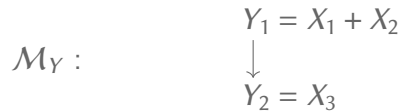
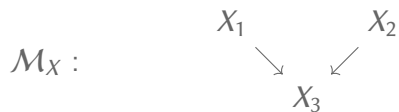
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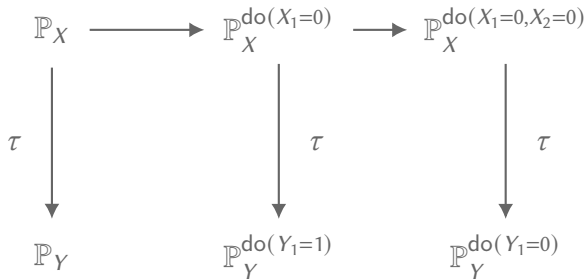
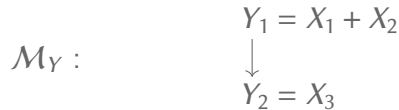
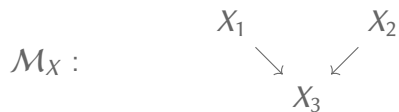
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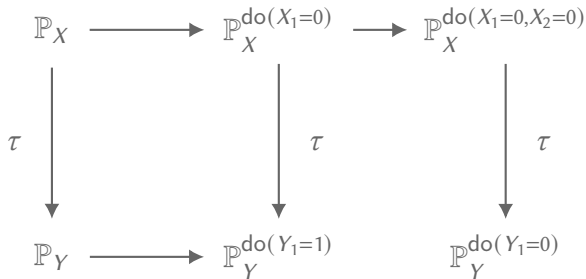
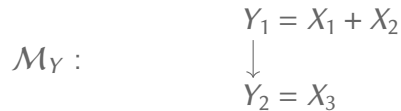
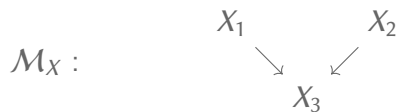
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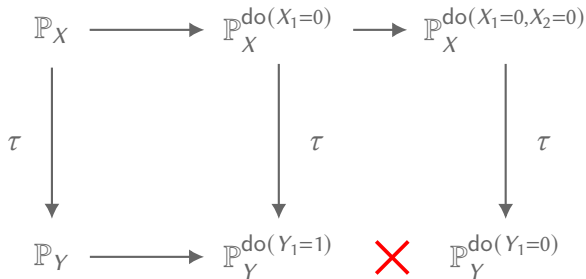
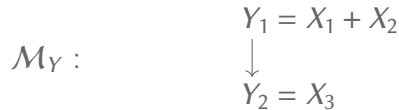
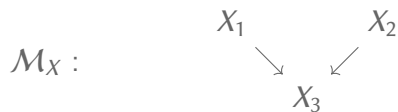
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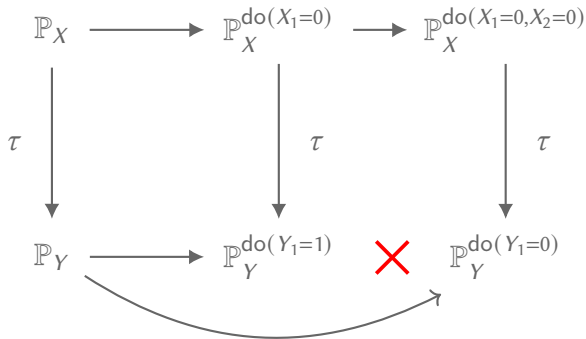
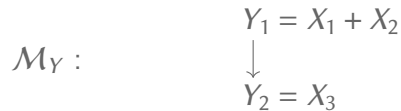
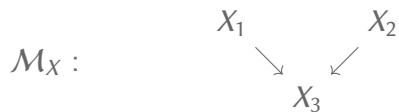
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Exact Transformations ensure Causally Consistent SCMs



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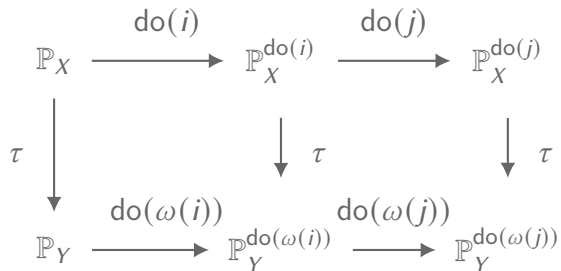
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$\implies \mathcal{M}_X$ and \mathcal{M}_Y are causally consistent



Causal Consistency



Elementary Properties of Exact Transformations

Lemma

The identity mapping is an exact transformation.

$$\mathcal{M}_X \xrightarrow{\text{id}} \mathcal{M}_X$$

Lemma

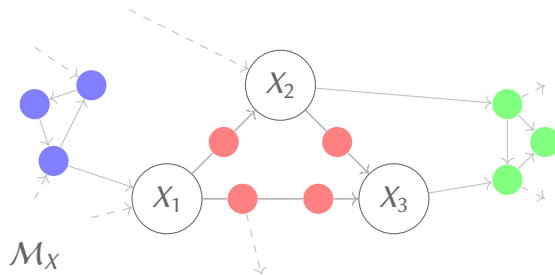
Exact transformations are transitively closed.

$$\begin{array}{ccccc} \mathcal{M}_X & \xrightarrow{\tau_1} & \mathcal{M}_Y & \xrightarrow{\tau_2} & \mathcal{M}_Z \\ & \searrow & \text{ } & \nearrow & \\ & & \tau_2 \circ \tau_1 & & \end{array}$$



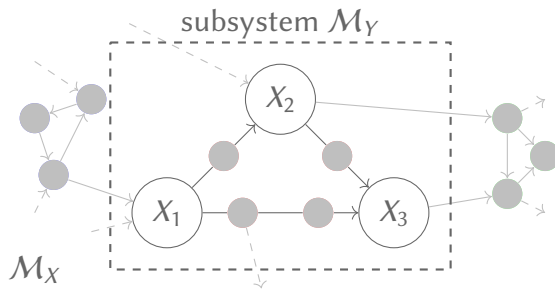
Few Transformations yield Causally Consistent Representations ⚡

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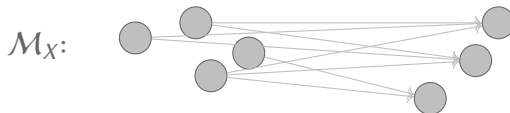
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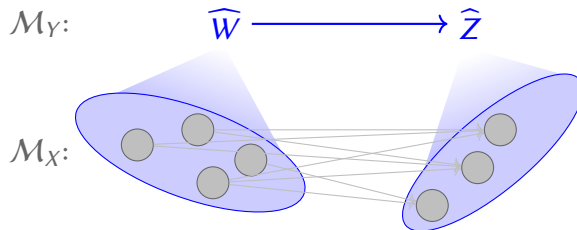
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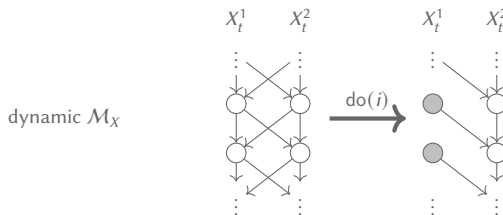
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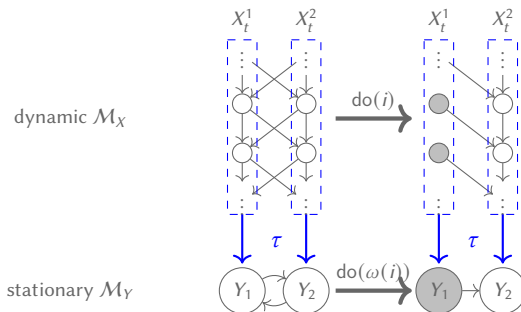
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Challenges for *Causally Consistent* Representation Learning



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